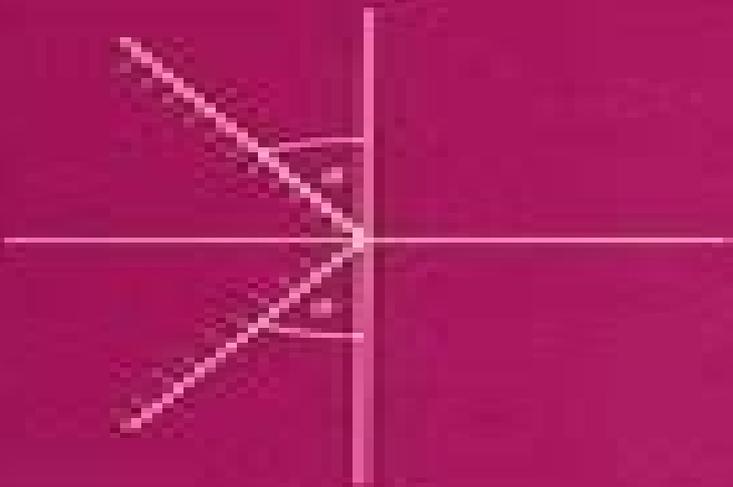
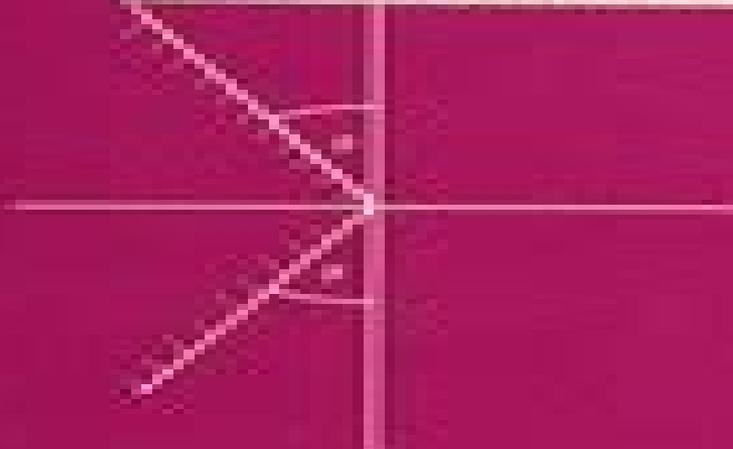




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Computational Aspects of Linear Control Claude Brezinski, 2013-12-01 Many devices we say dynamical systems or simply systems behave like black boxes they receive an input this input is transformed following some laws usually a differential equation and an output is observed The problem is to regulate the input in order to control the output that is for obtaining a desired output Such a mechanism where the input is modified according to the output measured is called feedback The study and design of such automatic processes is called control theory As we will see the term system embraces any device and control theory has a wide variety of applications in the real world Control theory is an interdisciplinary domain at the junction of differential and difference equations system theory and statistics Moreover the solution of a control problem involves many topics of numerical analysis and leads to many interesting computational problems linear algebra QR SVD projections Schur complement structured matrices localization of eigenvalues computation

of the rank Jordan normal form Sylvester and other equations systems of linear equations regularization etc root localization for polynomials inversion of the Laplace transform computation of the matrix exponential approximation theory orthogonal polynomials Padé approximation continued fractions and linear fractional transformations optimization least squares dynamic programming etc So control theory is also a good excuse for presenting various sometimes unrelated issues of numerical analysis and the procedures for their solution This book is not a book on control

Robust Industrial Control Systems Michael J. Grimble, 2006-05-01 Robust Industrial Control Systems Optimal Design Approach for Polynomial Systems presents a comprehensive introduction to the use of frequency domain and polynomial system design techniques for a range of industrial control and signal processing applications The solution of stochastic and robust optimal control problems is considered building up from single input problems and gradually developing the results for multivariable design of the later chapters In addition to cataloguing many of the results in polynomial systems needed to calculate industrial controllers and filters basic design procedures are also introduced which enable cost functions and system descriptions to be specified in order to satisfy industrial requirements Providing a range of solutions to control and signal processing problems this book Presents a comprehensive introduction to the polynomial systems approach for the solution of H_2 and H_∞ optimal control problems Develops robust control design procedures using frequency domain methods Demonstrates design examples for gas turbines marine systems metal processing flight control wind turbines process control and manufacturing systems Includes the analysis of multi degrees of freedom controllers and the computation of restricted structure controllers that are simple to implement Considers time varying control and signal processing problems Addresses the control of non linear processes using both multiple model concepts and new optimal control solutions Robust Industrial Control Systems Optimal Design Approach for Polynomial Systems is essential reading for professional engineers requiring an introduction to optimal control theory and insights into its use in the design of real industrial processes Students and researchers in the field will also find it an excellent reference tool

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extensive knowledge on the topics including students with control background who are interested in polynomial fuzzy model based control systems

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Matrix and Polynomial Approach to Dynamic Control Systems Dai-Zhan Cheng, 2002 This book introduces a new framework which develops a matrix and polynomial approach to dynamic systems particularly non linear control systems This new approach will treat dynamic systems and non linear control problems in a linear way Preface p v

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SIAM Journal on Control and Optimization Society for Industrial and Applied Mathematics, 1998

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